
SpartanMC

***Parallel Input/Output for 1 to 18
Bit (port_bi)***

Table of Contents

1. Module Parameters	1
2. Interrupts	1
3. Peripheral Registers	2
3.1. PORT_BI Register Description	2
3.2. PORT_BI C-Header for Register Description	3

List of Figures

List of Tables

0 Bidirectional port module parameters	1
0 PORT_BI registers	2

Parallel Input/Output for 1 to 18 Bit (port_bi)

The bidirectional port module provides up to 18 inputs or outputs. Each signal pin can be configured through the corresponding bit in the control registers (PIN_BI_DIR, PIN_BI_OE). If configured as input they can be used to generate interrupts (triggered by a raising or falling edge) on the SoC inputs. If configured as output the pins can be drove in open drain mode or as tri-state output. (The usage in open drain mode requires at least one pull up resistor.)

1. Module Parameters

Table 1: Bidirectional port module parameters

Parameter	Default Value	Description
BASE_ADR		Start address of the memory mapped peripheral registers. The value is taken as offset to the start address of the peripheral memory space. This parameter is set by jConfig automatically.
PORT_WIDTH	18	Number of Input/Output Bits.
OD_OUTPUT	0	Specify the output mode (0 = tri-state output, 1 = open drain output).

2. Interrupts

An interrupt signals will be generated for each enabled PORT_BI bit. To delete the interrupt flag a read access on PIN_BI_DAT, PIN_BI_IR_EDGSEL, PIN_BI_IE, PIN_BI_DIR or PIN_BI_OE is required.

3. Peripheral Registers

3.1. PORT_BI Register Description

The bidirectional port peripheral provides six 18 bit registers which are mapped to the SpartanMC address space e.g. $0x1A000 + \text{BASE_ADR} + \text{Offset}$.

Table 2: PORT_BI registers

Offset	Name	Access	Description
0	PIN_BI_DAT	read/ write	Register for incoming or outgoing data.
1	PIN_BI_IE	read/ write	Enables the interrupts on PIN_BI_DAT register. After system reset all PIN_BI_IE bits are initialized with zero.
2	PIN_BI_OE	read/ write	If set to one the corresponding output pin in PIN_BI_DAT is enabled. After system reset all PIN_BI_OE bits are initialized with zero.
3	PIN_BI_DIR	read/ write	Specify the direction (input/output) of the port signal. After system reset all PIN_BI_DIR bits are initialized with zero.
4	PIN_BI_EDGSEL	read/ write	Specify the input edge which triggers the interrupt (0 = falling edge, 1 = raising edge) After system reset all PIN_BI_EDGSEL bits are initialized with zero.
5	PIN_BI_IR_STATUS	read	Register for interrupt flags. If set to one it indicates an interrupt on the corresponding input pin. The interrupt flag will be deleted with a read access on all other module registers except this one. After system reset all PIN_BI_IR_STATUS bits are initialized with zero.

3.2. PORT_BI C-Header for Register Description

```
#ifndef PORT_BI_H_
#define PORT_BI_H_

#define IO00 (1 << 0)
#define IO01 (1 << 1)
#define IO02 (1 << 2)
#define IO03 (1 << 3)
#define IO04 (1 << 4)
#define IO05 (1 << 5)
#define IO06 (1 << 6)
#define IO07 (1 << 7)
#define IO08 (1 << 8)
#define IO09 (1 << 9)
#define IO10 (1 << 10)
#define IO11 (1 << 11)
#define IO12 (1 << 12)
#define IO13 (1 << 13)
#define IO14 (1 << 14)
#define IO15 (1 << 15)
#define IO16 (1 << 16)
#define IO17 (1 << 17)

typedef struct port_bi {
    volatile unsigned int data; // (r/w) (r = reset-int)
    volatile unsigned int ie; // (r/w) (r = reset-int)
    volatile unsigned int oe; // (r/w)
    volatile unsigned int dir; // (r/w) (r = reset-int)
    volatile unsigned int edgsel; // (r/w) (r = reset-int)
    volatile unsigned int ir_stat; // (r)
} port_bi_t;

#endif /*PORT_BI_H_*/
```